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# WRITING TEMPLATE: TECHNICAL ANALYSIS REPORT

TITLE: COMPARATIVE ANALYSIS OF SENSOR TECHNOLOGIES IN AUTONOMOUS VEHICLES		
STUDENT NAME:DATE:		
I. Introduction		
<ul> <li>State the purpose of your report.</li> <li>Introduce the sensors you will compare (at least of the sensor technology is essential)</li> </ul>	•	
Example Starter:  This technical analysis compares several sensor tech,, and		
systems detect obstacles, measure distance, and na		
II. Sensor Overview and Functions		
Sensor Type	How It Works	
Infrared Sensor		
Ultrasonic Sensor		
LiDAR		
Camera / Vision System		
Radar		
GPS / Gyroscope		

Add rows or remove as needed.



Name:	
Period:	
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# **III. Comparative Analysis**

Use this section to compare your selected sensors in detail.

#### **Guiding Prompts:**

- Which sensors have the greatest range or accuracy?
- Which are most cost-effective or environmentally adaptable?
- How do these sensors work together in a robotic car?

### **Example Starter:**

LiDAR and camera systems both provide visual data, but LiDAR offers more precise 3D mapping, while cameras deliver detailed color recognition. In contrast, ultrasonic sensors are best for short-range detection during parking or low-speed navigation.

IV. Evaluation of Strengths and Limitations

Sensor Type	Advantages	Limitations
LiDAR		
Ultrasonic		
Camera		

#### V. Conclusion and Recommendation

Summarize your findings and make a final recommendation.

### **Guiding Prompts:**

- Which sensor or combination of sensors provides the best overall performance?
- Why is using multiple sensors beneficial for safety and precision?



Name:	
Period:	

Exampl	e Sta	rter:
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Based on this analysis, the	nost effective configuration for autonomous vehicles combines
and	sensors. This combination ensures accuracy in distance detection and
strong environmental awar	eness under varying conditions.

## VI. TECHNICAL VOCABULARY USED

List at least three technical terms from your research and define them in your own words.

Term	Definition (in your own words)